# Lab 09 - Chapter 9 <br> I. El-Shaarawy \& M. Touny 

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## Exercises

### 9.1.1

## Hints.

- Use quotient and mod operations.
- Observe why the quotient yields the maximum possible count of some coin.


## Solution.

```
# input: non negative amount n, and a decreasing array of coins D
# output: array C where C[i] is number of coins of ith denomination D[i]
def greedyCoins(integer n, D[1..m])
    # for each coin
    for i in 1..m
        # take max possible number of it
        C[i] = floor( n/D[i] )
        # remaining amount for next iteration
        n = n \mod D[i]
    # if there is still a remaining amount
    if n != 0 return "no solution"
    # otherwise given n is partitioned by coins
    return C
```


### 9.1.15

## Homework.

### 9.2.3

## Hints.

- Observe Kruskal works with global edges, unlike Prim which searches within local neighbour edges.
- What is error you think we will encounter upon running Kruskal on a a tree with more than one component?
- Why does looping on $|V|-1$ works in Kruskal?
- Modify the while condition to accommodate any forest.


## Solution.

Modify the while condition in Kruskal to be ecounter < $|E|$, So it terminates if there are no more edges.

Bonus. Modify Prim then use it as a subroutine to solve the general forest case.

### 9.2.5

## Homework.

### 9.3.1

## Hints.

- (c) Use Transform-and-conquer strategy.
- (c) Fixing vertices, What kind of modification is required on edges?
- (d) Use Transform-and-conquer strategy.
- (d) We will use Dijkstra as a subroutine, So the graph will be transformed to the usual form given in the book.


## Solution.

## (a)

A data structure which considers directed edges.
(b)

Same algorithm. You may terminate once you find the destination.

## (d)

Each vertex $v_{i}$ is mapped to $v_{i}^{s t}$ and $v_{i}^{e n}$, with directed edge $\left(v_{i}^{s t}, v_{i}^{e n}\right)$ whose weight is the number labeled on $v_{i}$. Any vertex in $G$ neighbour to $v_{i}$, can travel to $v_{i}^{s t}$ but not $v_{i}^{e n}$ in $G^{\prime}$. Only vertices $v_{i}^{e n}$ but not $v_{i}^{s t}$ can travel to other vertices. Those edges in $G^{\prime}$ are assigned zero weights.

```
# input: graph G with weighted vertices
# output: graph G with weighted edges and no weighted vertices
def vertexWeightToEdgeWeight(G)
construct empty graph G,
for each vertex v in G(V)
    add vertex v_st to G'
    add vertex v_en to G'
    set (v_st, v_en).weight to v.weight
    add edge (v_st, v_en) to G'
        for each edge e = {a,b} in G(E)
            set (a_en, b_st).weight = 0
        add edge (a_en, b_st) to G'
        set (b_en, a_st).weight = 0
```

```
    add edge (b_en, a_st) to G'
return G'
```

(c)

Set the destination as source then reverse paths. If graph is directed reverse paths before running the algorithm also.

```
# input: graph G
# output: same graph but whose edges are reversed
def reverseEdges(G)
    construct empty graph G'
    clone vertices G'(V) = G(V)
    for every vertex v in G(V)
        for every edge e = (v,t) in G(E)
                add edge (t,v) to G'
    return G'
# input: undirected graph G, destination d
# output: shortest-paths of given d
def undirectedGraphSingleDistination(G, d)
    compute Dijkstra(G, d) in graph G
    return reverseEdges(G)
# input: directed graph G, destination d
# output: shortest-paths of given d
def directedGraphSingleDestination(G, d)
    G = reverseEdges(G)
    compute Dijkstra(G, d) in graph G
    return reverseEdges(G)
```


## Homework.

A data-structure based implementation is left to students. In fact this is an excellent illustration of abstraction in algorithm design.

### 9.3.7

Homework.
9.4.5

Homework.

### 9.4.7

## Hints.

- A basic recursive algorithm traversal works.


## Solution.

```
def allHuffmanCodes(root)
    if root is NULL
        return [ ]
    # if root is a leaf
    if root.rightChild is NULL and root.leftChild is NULL
        return [ root.character ]
    # if exactly one child is NULL, Concatenating an empty list does no harm
    childCodes = allHuffmanCodes(root.leftChild) + allHuffmanCodes(root.rightChild)
    # prefix each code in child with root's character
    return [ root.character + code for code in childCodes ]
```

We leave it to students to modify the algorithm so that it generates a 2 d -array of symbolscodes as a homework.

